

# Different Types of Fast Frequency Response from Inverter-based Resources

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# Agenda

- 1 Background**

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- 2 What is Fast Frequency Response?**

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- 3 Characteristics of FFR and Their Impact**

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- 4 Analytical Prediction of Frequency Nadir**

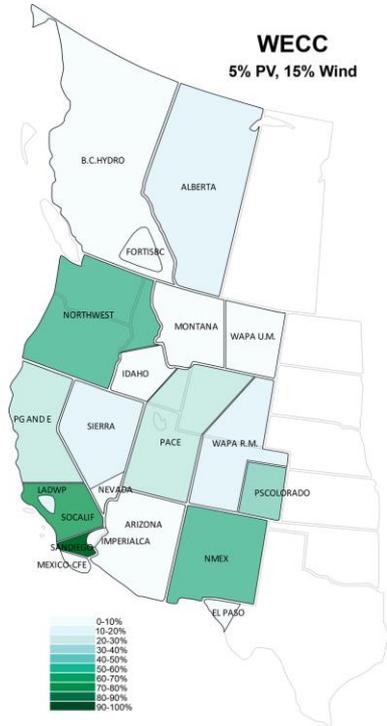
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- 5 Fast Frequency Nadir Prediction for Real-time Operation**

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- 6 Develop Stability Constraints in Scheduling with Various FFRs**

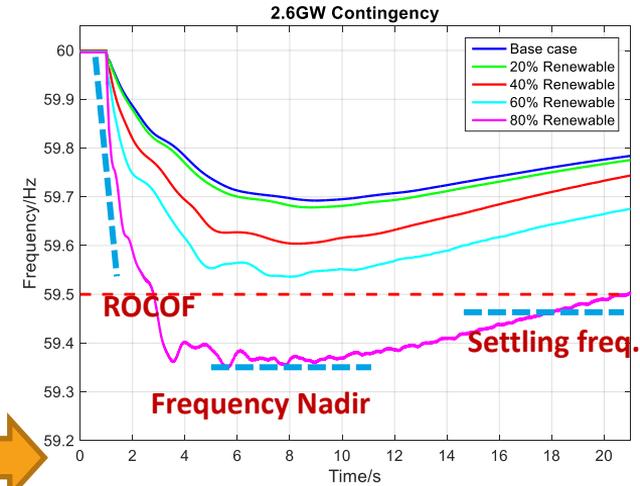
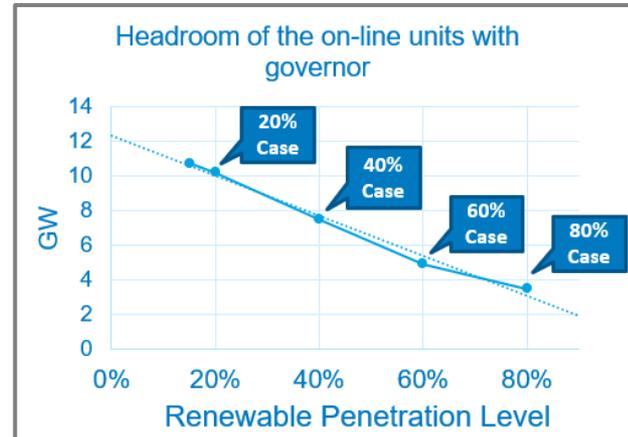
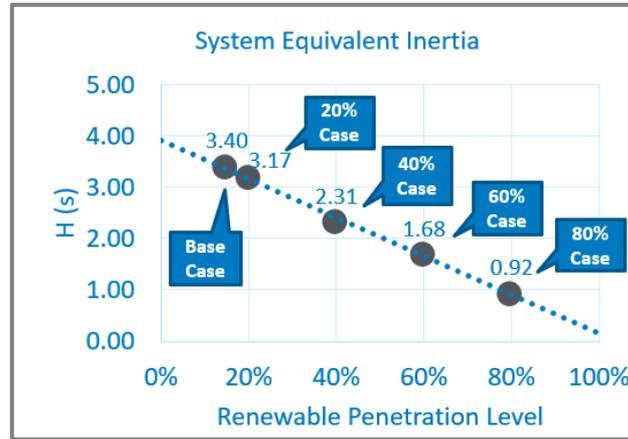
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- 7 Conclusion**

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# High Renewable Penetrated Grid Requires Fast Frequency Response



Renewable Penetration  
(20%, 40%, 60%, 80%)



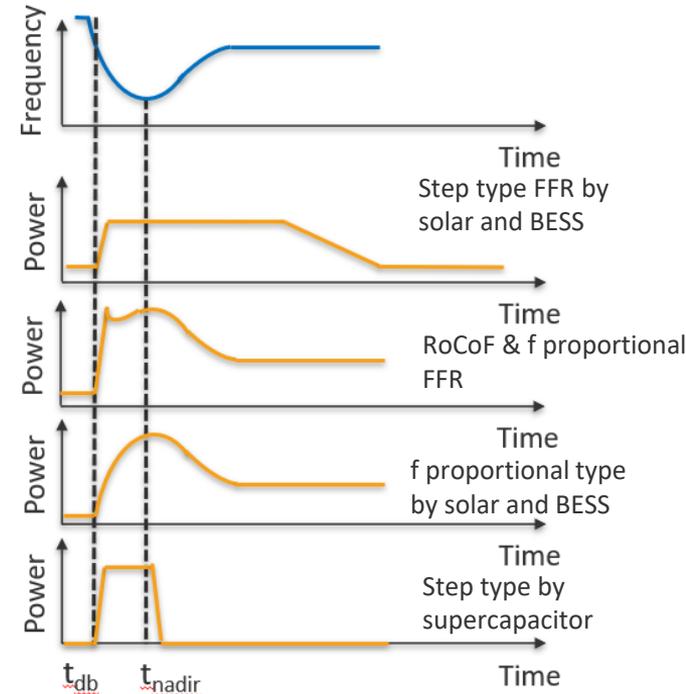
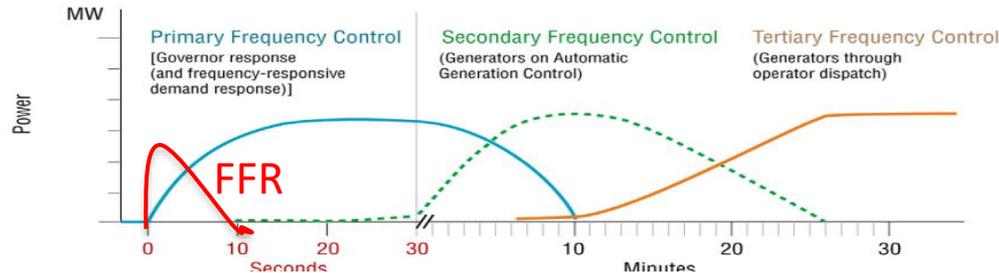
- ☹ High rate of change of frequency (ROCOF)
- ☹ Low frequency nadir
- ☹ Low settling frequency

# What is Fast Frequency Response?

- Different technologies can have different forms of Fast frequency response (FFR)
  - Response type; Trigger; trajectory

Action	Response Type	Trigger Condition
Active Power Injection Or Load Reduction	Step	frequency threshold
		RoCoF threshold
		contingency event
	Proportional	to frequency error
		to RoCoF

## How to quantify various types of FFR capability from IBRs during the planning and operation?

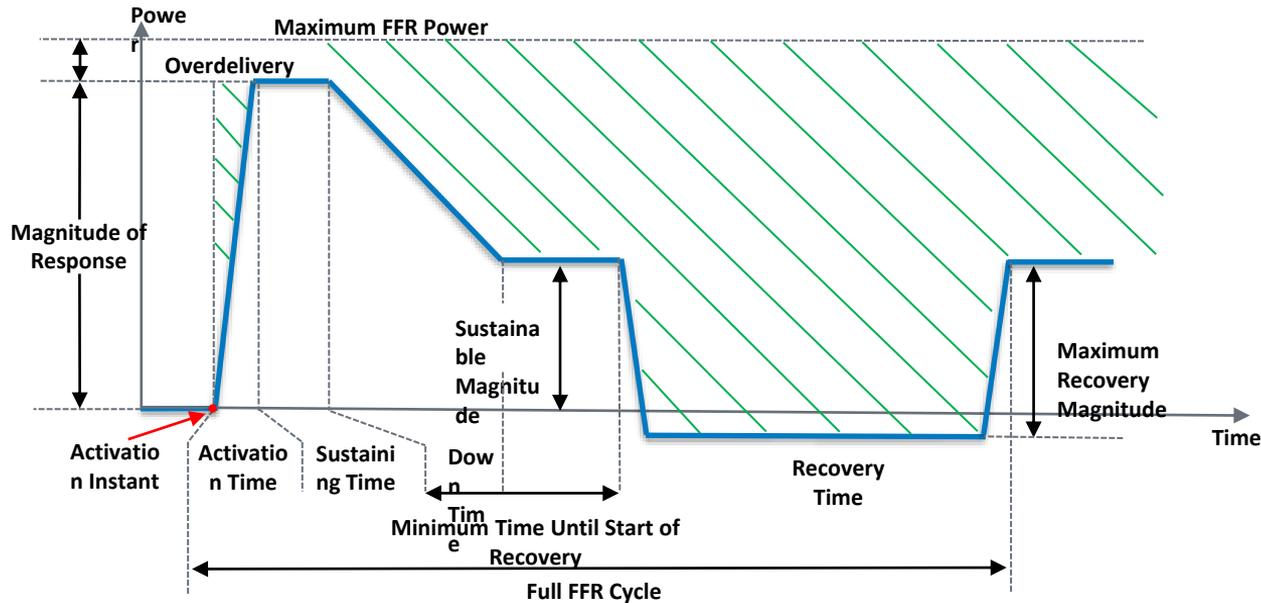


NERC. "Fast frequency response concepts and bulk power system reliability needs". 2020.

# Characteristics of Fast Frequency Response

- **3H** - How fast, How much and How long?

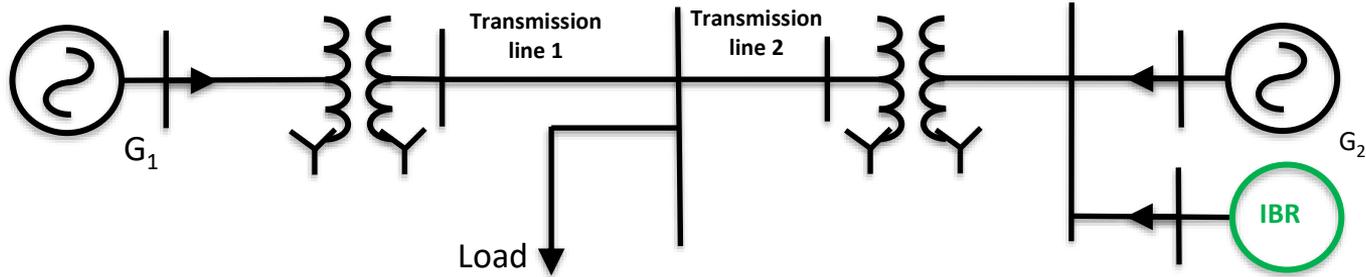
## Key features of the fast frequency response (FFR) trajectory



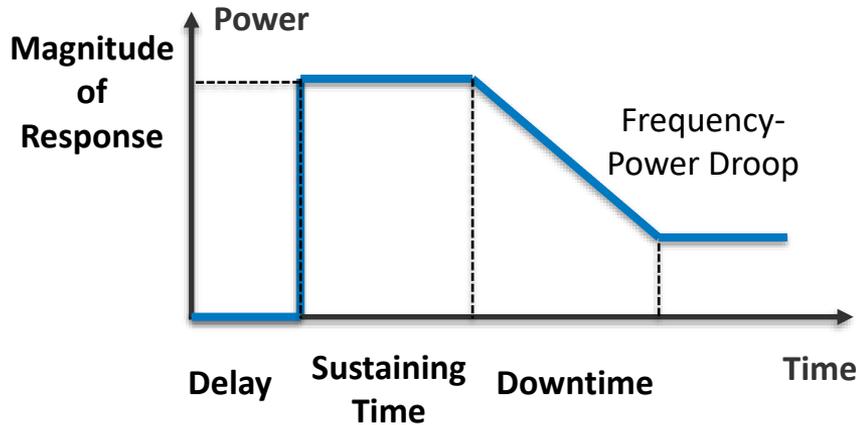
## Four factors

- Speed of response (i.e., response time)
- Magnitude of response
- Sustaining time
- Downtime

# Start with a Simple Test System and a Generalized form of FFR



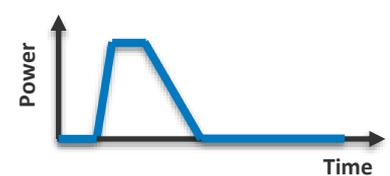
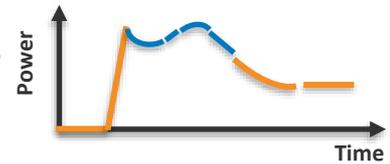
## A generalized form of FFR



Frequency-dependent magnitude of response

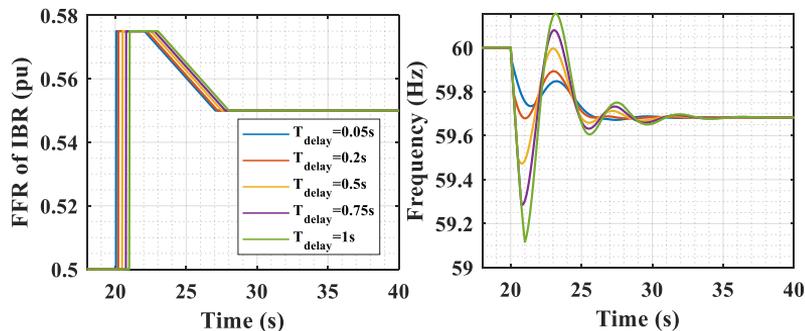
Very long sustaining time

Short sustaining time, no frequency-power droop



# Impact of Key Fast Frequency Response Factors (Con't)

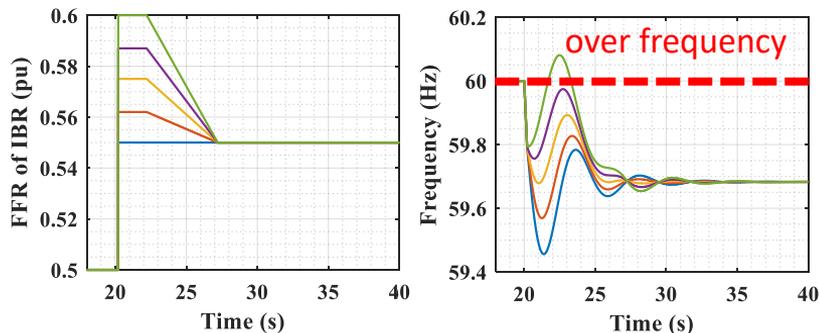
## Impact of Speed of Response



## Findings

- Fast response always significantly increases the nadir.
- If  $T_{\text{delay}} < 0.2\text{s}$ , the nadir is not sensitive to the response speed anymore.
- **The faster, the better.**
- **No need to be super fast.**

## Impact of Magnitude of Response

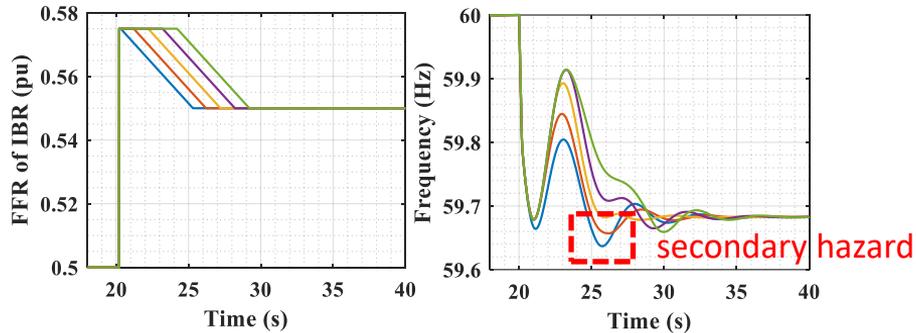


## Findings

- High response magnitude decreases the RoCoF and increases the nadir.
- Excessively high response magnitude can even cause over frequency and exacerbate the “secondary hazard”.
- **Not always the larger, the better → over frequency issues**

# Impact of Key Fast Frequency Response Factors

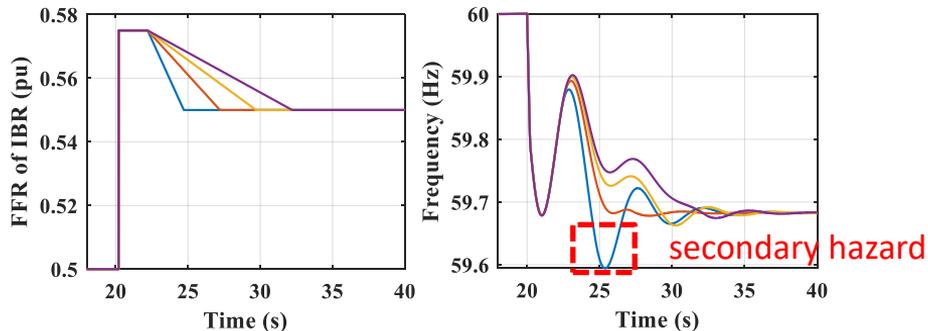
## Impact of Sustaining Time



### Findings

- Sustaining time doesn't affect the RoCoF.
- $T_{\text{sus}} < 1\text{s}$ ,  $T_{\text{sus}} \downarrow$ , nadir  $\downarrow$
- $T_{\text{sus}} > 1\text{s}$ ,  $T_{\text{sus}} \uparrow$ , nadir  $\rightarrow$
- **Secondary hazard:** the frequency drop caused by the ending of FFR.
- Needs to be long enough.
- No need to be super long.

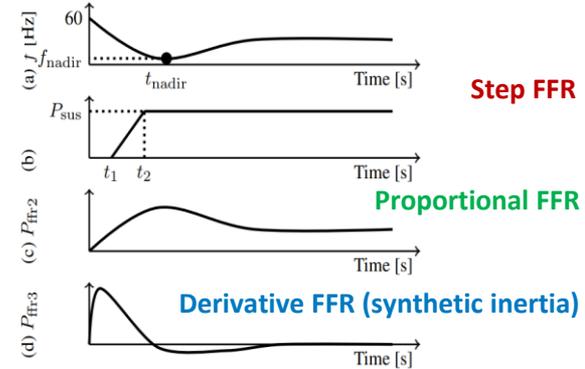
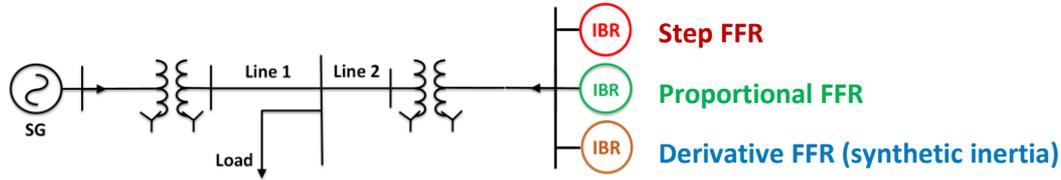
## Impact of Downtime



### Findings

- Down time doesn't affect the RoCoF.
- Given sustaining time = 2s, fast downtime doesn't affect the Nadir.
- **The fast downtime can cause the "secondary hazard".**
- The slower, the better.
- Too fast might cause a secondary hazard
- Too slow can cause a long settling time.

# Analytical Prediction of Frequency Nadir



Model power system frequency dynamics

$$2H_g \frac{df}{dt} = P_m - P_{\text{load}} - D_g(f - f_n) + (P_{\text{ffr1}} + P_{\text{ffr2}} + P_{\text{ffr3}}),$$

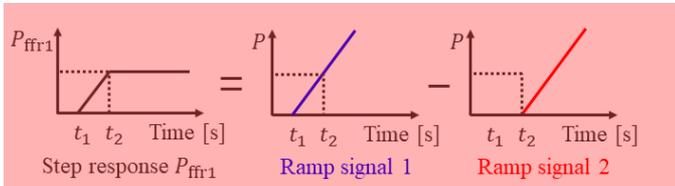
$$T_m \frac{dP_m}{dt} = P_m + \frac{1}{R_g}(f - f_n),$$

Proposed **analytically predict the frequency nadir**  $\Delta f_{\text{nadir}}$  as follows



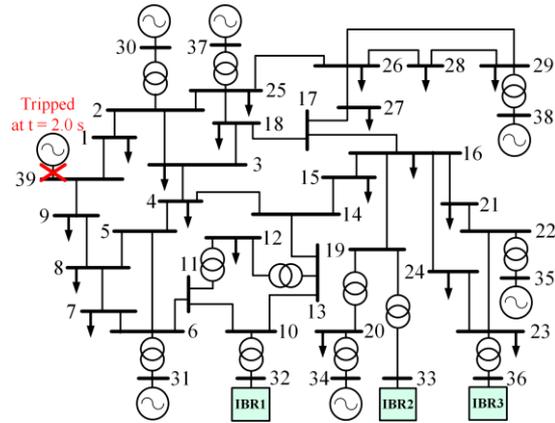
$$\Delta f_{\text{nadir}} = \frac{P_{\text{sus}} - \Delta P_{\text{load}}}{D_{\Sigma} + R_g^{-1}} + \frac{T_g R_g^{-1} M e^{(\alpha - \phi - \pi) \cos \phi}}{(t_2 - t_1)(D_{\Sigma} + R_g^{-1})^{3/2}},$$

where  $P_{\text{sus}}$ ,  $\Delta P_{\text{load}}$ ,  $D_{\Sigma}$ ,  $R_g$ ,  $T_g$ ,  $M$ ,  $\alpha$ ,  $t_1$ ,  $t_2$ , and  $\phi$  depend on system parameters.



$$P_{\text{ffr2}} = -\frac{1}{R_{\text{ibr}}}(f - f_n), P_{\text{ffr3}} = -H_{\text{ibr}} \frac{df}{dt}.$$

# Application I: Fast Frequency Nadir Prediction for Real-time Operation

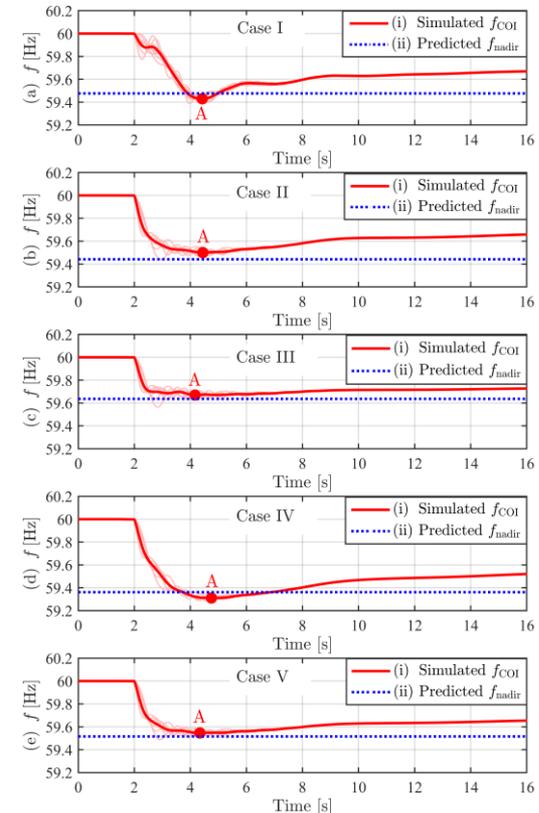


Modified 39-bus system with three types of FFR from IBRs

Case	Bus32	Bus33	Bus36
I	SG	SG	SG
II	$P_{ffr1}$	$P_{ffr1}$	$P_{ffr1}$
III	$P_{ffr2}$	$P_{ffr2}$	$P_{ffr2}$
IV	$P_{ffr3}$	$P_{ffr3}$	$P_{ffr3}$
V	$P_{ffr2}$	$P_{ffr3}$	$P_{ffr1}$

Case I-V: IBR1-3 provides different combination of FFRs

- **High accuracy:** The predicted frequency nadirs (blue dotted line) in cases I-V are close to the simulated ones (point A) with error smaller than **0.06 Hz**.
- **High efficiency:** Our frequency nadir prediction method takes **0.15 ms** while the EMT simulation requires **~1000 s (10<sup>6</sup> times acceleration)**.



# Application II: Develop Stability Constraints in Scheduling

**Question:** How to utilize fast frequency response capabilities from IBRs?

- **Fast Frequency Reserve**
- **Frequency-nadir Stability Constraints**

**Challenges:**

- How to apply the analytical method to a real large-scale system? How accurate it is?
  - Different types of SG governors (TGOV1, and GGOV1)
  - The response time of IBRs
  - A linearized constraint between key parameters needs to be discovered.

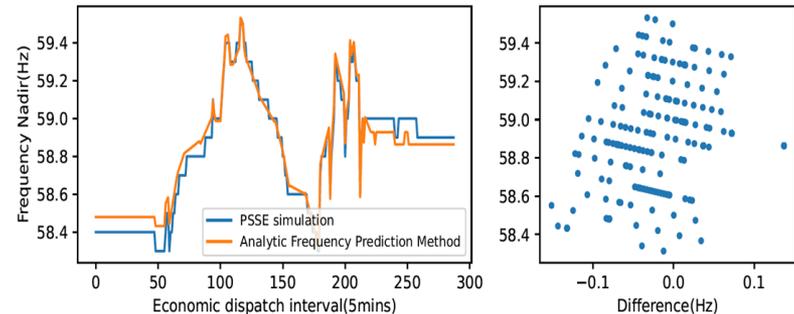
**Step 1: Develop low-order frequency response model for TGOV1, GGOV1 and IBRs**



**Step 2: Improve the aggregated system frequency response model (ASFR)**



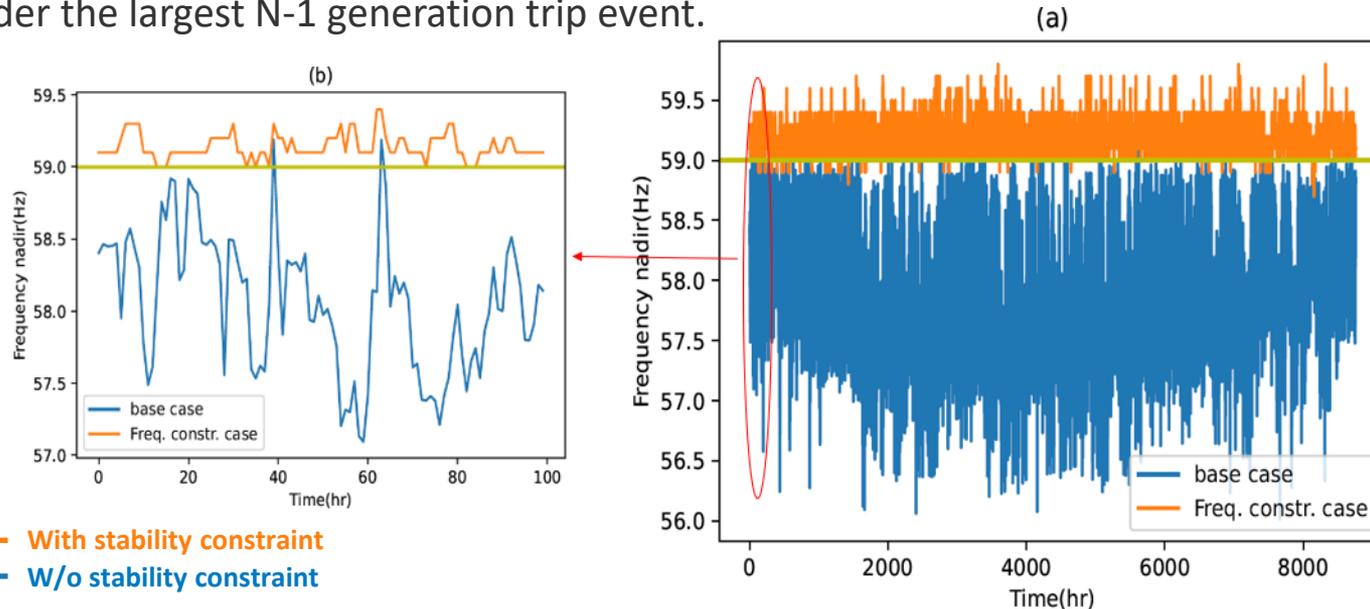
**Step 3: Comparison of  $f_{\text{nadir}}$  in simulation and analytical method for a real Island Grid**



# Application II: Verification of Proposed Constraint in Island Power Systems

**Test system:** A real island power system with a 70% renewable energy penetration level.

**Scenarios:** One-year test with and without stability constraints in the optimal scheduling model under the largest N-1 generation trip event.

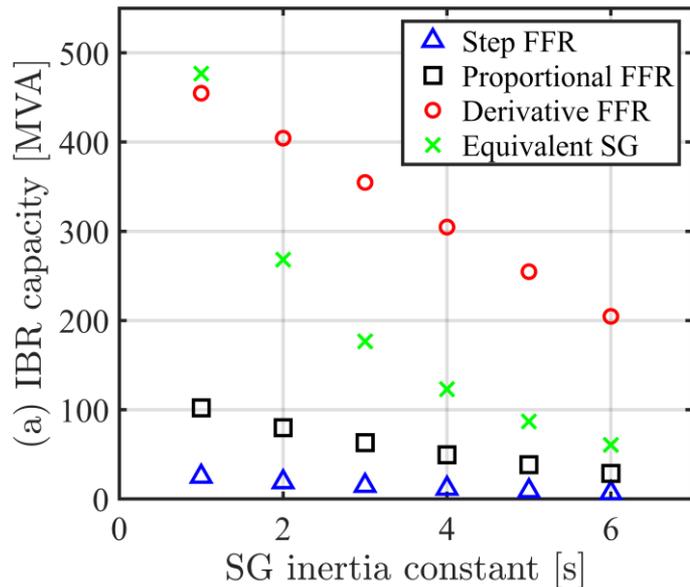


With the proposed frequency stability constraint, 98% of the system's frequency nadir is above 59.0 Hz.

# FFR quantifications: IBR v.s. SGs

Increase SG inertia from 1 s to 6 s and plot the required FFR1, FFR2, and FFR3 IBR as well as SG capacity of achieving 59.5 Hz nadir.

- Step FFR (**FFR1**): reaction time 0.02 s and ramp-up time 0.05 s.
- Proportional FFR (**FFR2**): IBR P/f droop is 3%.
- Derivative FFR (**FFR3**): IBR inertia is 6 s.



When the renewable penetration level is high ( $H=1s$ )

- 1 **FFR1**=19 SGs
- 1 **FFR2**=5 SGs
- 1 **FFR3**=1 SG

When the renewable penetration level is medium/low ( $H=3s$ )

- 1 **FFR1**=12 SGs
- 1 **FFR2**=3 SGs
- 1 **FFR3**=0.5 SG
- **Step FFR1** is the most effective type of FFR.
- We recommend combining **FFR2** and **FFR3** for the FFR service.

# Concluding Remarks

- Needs for Fast Frequency Response have been growing along with the high renewable integration. Various types of FFR bring challenges for FFR quantification.
- We developed a **fast** and **accurate** method to analytically predict post-disturbance frequency nadir in power systems with both SGs and IBRs. All **three major types of FFR from IBRs** are fully considered in our improved system frequency response (SFR) model.
- The proposed FFR quantification method can be used for
  - **Prediction of frequency nadir** in real-time operation or planning study.
  - **Developing stability constraints in the scheduling model** to ensure sufficient FFR resources online.

## Compelling future directions:

- More types of FFR will be added further, such as grid-forming inverters' responses (Droop-based, virtual synchronous machine, etc.).
- Evaluation of FFR capacity adequacy from IBRs in planning study.
- Application of frequency nadir prediction method in real-time power system security monitoring.

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## Team



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## Sponsor



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U.S. Department Of Energy

# Thank you!

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