

Future Role of Hybrid Simulations in Assessing the Dynamic Stability of IBR Dominated Power Systems

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Fall Technical Workshop

Brief Wallace History

NREL 2017 - 2022:

- Coupled T&D simulations

- Electro-magnetic (EMT) modeling of the Maui power system

PhD at University of Colorado, Boulder 2022: - Droop-e

Power Systems Simulation Lead at encoord

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Changing Power Systems

• New stability classification: 'Converter-driven Stability'

• Numerous oscillatory events with unusual, higher frequency spectrums being observed

A. Hoke, V. Gevorgian, S. Shah, P. Koralewicz, R. W. Kenyon, and B. Kroposki, "Island Power Systems With High Levels of Inverter-Based Resources: Stability and Reliability Challenges," *IEEE Electrification Magazine*, vol. 9, no. 1, pp. 74–91, Mar. 2021.

Fundamental Device Differences – Simulation Perspective

Synchronous Generators; partitioned / narrow bandwidth

- Natural timescale separation; predictable
- Physics dominated dynamics
- Rotors yield deterministic local bus frequencies
- Dovetails with quasi-static phasor (QSP) simplifications

Inverter-based Resources; continuous / wide bandwidth

- Cascaded PI controllers; no 'natural' separation
- Current controller feedback; interacts with network transients
- Mathematically, tend to negate some of the QSP simplifications

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A PSCAD Story

Generic Inverter Models

Open source / Scalable

Filter dynamics

Current/power/voltage controllers

Limiting / DC - side dynamics

R. W. Kenyon, A. Sajadi, A. Hoke, and B.-M. Hodge, "Open-Source PSCAD Grid-Following and Grid-Forming Inverters and A Benchmark for Zero-Inertia Power System Simulations," in *2021 IEEE Kansas Power and Energy Conference (KPEC)*, Apr. 2021, pp. 1–6.

The Maui System – Validated to Field Data

Reduced 2023 Maui Transmission Map:

PSCAD model built with generic inverter models.

Parallelized; 30 cores on a dedicated machine; hours for a 15 second simulation.

This is a SMALL system!

R. W. Kenyon, B. Wang, A. Hoke, J. Tan, C. Antonio, and B.-M. Hodge, "Validation of Maui PSCAD Model: Motivation, Methodology, and Lessons Learned," in *2020 52nd North American Power Symposium (NAPS)*, Apr. 2021, pp. 1–6.

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\text{or } 24 \\
\text{or } 6\n\end{array}$ $-$ PSCAD: Bus 602 PSSE: Bus 602 -PSCAD: Bus 303 - PSSE: Bus 303 - PSCAD: PLL Bus 501 - PSSE: Bus 501 -PSCAD: Bus 301 - PSSE: Bus 301 $58 -$ - PSCAD: SC 501a - PSSE: SC 501a - PSCAD: Bus 501 - PSSE: Bus 501 $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ (a) S1: Frequency (b) S1: Voltage 12 PSCAD: Bus 602 - PSSE: Bus 602 - PSCAD: Bus 303 - PSSE: Bus 303 -PSCAD: PLL Bus 501 -PSSE: Bus 501 -PSCAD: Bus 301 - PSSE: Bus 301 -68 - PSCAD: SC 501a - PSSE: SC 501a - PSCAD: Bus 501 - PSSE: Bus 501 $\frac{1}{2}$ $\frac{1}{3}$ $\frac{1}{4}$ $\frac{1}{5}$ $\frac{1}{6}$ $\frac{1}{3}$ $\frac{1}{4}$ $\frac{1}{5}$ $\frac{1}{6}$ (d) S2: Voltage (c) S2: Frequency - PSSE: Bus 602 PSCAD: Bus 602 - PSCAD: Bus 303 - PSSE: Bus 303 PSCAD: PLL Bus 501 - PSSE: Bus 501 - PSCAD: Bus 301 ----- PSSE: Bus 301 58 - PSCAD: SC 501a -- PSSE: SC 501a PSCAD: Bus 501 -PSSE: Bus 501 $\frac{4}{1}$ 5 $\frac{1}{3}$ $\frac{1}{4}$ Time (s) (f) S3: Voltage (e) S3: Frequency

S1-> S5: march towards fewer voltage forming devices

Oscillations present after synchronous machines were removed - S3 (66% MVA reduction)

R. W. Kenyon, B. Wang, A. Hoke, J. Tan, and B.-M. Hodge, "Comparison of Electromagnetic Transient and Phasor Dynamic Simulations: Implications for Inverter Dominated Systems," in *2023 IEEE Power & Energy Society Innovative Smart Grid Technologies Conference (ISGT)*, IEEE, 2023, pp. 1–5.

PSCAD vs. Itself

Power and Current contains current controller/output filter

Power, a rough QSP type device level proxy?

All types with a phase-locked loop

Systematic reduction of only the **DG** inverter models 171 devices; ~100 MVA aggregate rating

R. W. Kenyon, A. Sajadi, A. Hoke, and B.-M. Hodge, "Criticality of Inverter Controller Order in Power System Dynamic Studies – Case Study: Maui Island," *Electric Power Systems Research*, vol. 214, p. 108789, Jan. 2023, doi: [10.1016/j.epsr.2022.108789.](https://doi.org/10.1016/j.epsr.2022.108789)

PSCAD vs. Itself

An anecdote; a single GFM device (another paper) solved this oscillatory issue in the full model.

R. W. Kenyon, A. Sajadi, A. Hoke, and B.-M. Hodge, "Criticality of Inverter Controller Order in Power System Dynamic Studies – Case Study: Maui Island," *Electric Power Systems Research*, vol. 214, p. 108789, Jan. 2023, doi: [10.1016/j.epsr.2022.108789.](https://doi.org/10.1016/j.epsr.2022.108789)

So Where Does This Leave Us?

o **System-wide, EMT type simulations are an enormous effort to develop, and extremely computationally intensive to run.**

o **Some of the bedrock simplifications of QSP type simulations also simplify pertinent, controller driven dynamics.**

o **QSP approaches are still vastly applicable, but there are operational periods that undeniably demand more detail.**

Co-simulation? Exchanging Between Tools

EMT when detail is needed; QSP when it is not.

These are challenging…

- separate simulation / software tools
- boundaries, boundaries, boundaries
- interfaces / network equivalents

Our Research: Hybrid Simulations

As a formulation solution

Intra-simulation Detail Modifications

If full order models are introduced (all detail is available), can intrasimulation singular perturbation / manifold type reductions be made?

Singular perturbation on the fly: an adaptive application

 $\dot{x}_s = F_s(x, \eta, \epsilon)$ $\epsilon \dot{x}_f = F_f(x, \eta, \epsilon)$ $\epsilon \rightarrow f(t)$?

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Autonomous Boundary Identification

Topological / temporal tracking

Metrics:

- voltage forming capacity and/or inertia
- short circuit ratio
- zero sequence magnitudes

Analytic:

- high frequency components
- impedance spectroscopy
- larger state rate of changes

Computational Structure

Will interface handling be inherent within the computational structure?

Variable, partitioned approach:

 $\dot{x}_m = f_m(x_m, y_n, \eta, t)$ $\mathbf{0}_n = g_n(x_m, y_n, \gamma, t)$ $\boldsymbol{m^t}$ + $\boldsymbol{n^t}$ = \boldsymbol{P} , $\forall \boldsymbol{t}$

Simultaneous, with coefficient updating

Goal is a Native, Hybrid Simulation Tool

• Building dynamic simulation capabilities; *a great time to ask foundational questions!*

• Integrated into our existing, commercially available, SAInt software.

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